

Serial No. 10/720,657

Filed: November 24, 2003

Amendment to the Abstract

Please cancel the existing Abstract and substitute therefor the new Abstract on substitute page 28, attached as an appendix hereto.

ABSTRACT

In a jacking system for a marine platform, a plurality of hydraulic continuous linear motion motors are engageable with a plurality of marine platform supporting legs to provide relative motion between the platform and its supporting legs, and to also maintain the platform and its supporting legs locked in a stationary relationship. In the jacking system, the number of hydraulic piston/cylinder units and the number and design of the teeth that are engaged in providing relative motion may be selected to substantially reduce material stresses on the system.